

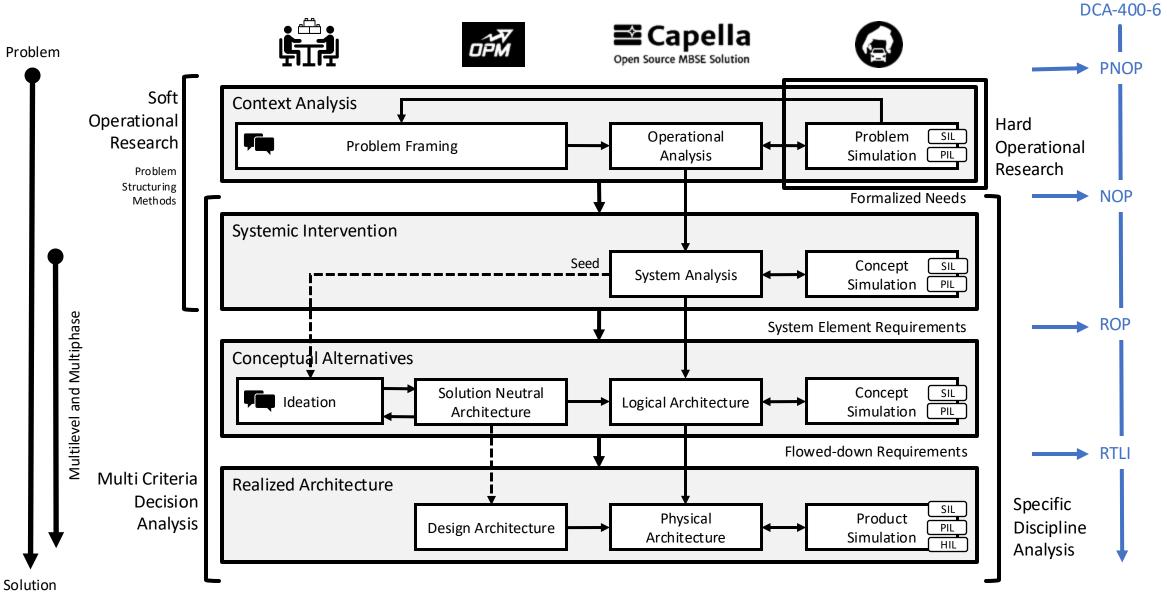
IEA-P – DEPARTAMENTO DE PROJETOS (PROJECT DEPARTMENT)

ARQUITETURA CONCRETA

	SEMAN	Α	TEORIA	INDIVIDUAL	PESO	GRUPO	PESO
	1	1	Estrutura e Filosofia do Curso				
	05-Aug	1	O que é Engenharia de Sistemas? INCOSE	AI-01 - Resumo Cap 1 -	100/		
	7		Elementos da Eng Sis.	HB INCOSE	10%		
			Introdução aos diagrams clássicos.				
	2		* (Viagem ao EUA)				
				AI-02 - Leitura/Resumo	100/		
				paper sobre representações clássicas.	10%		
	3		* (Viagem ao EUA)				
	19-Aug			AI-03 - Exercício sobre	1001		
				arquitetura e escrita de requisitos.	10%		
				iequisitos.			
	4	1	Metodologias de MBSE e uso de modelos.				
	26-Aug	1	Revisão de UML-SysML.	AI-04 - Resumo Artigo de	10%		
		1	OPM	Metodologias	10 /6		
		1	Arcadia				
_	5	1	ОРМ				
	02-Sep	1		AI-05 - Lista de exercícios	10%		
				AI-00 - LISIA de exelcicios	10 /8		
		1					
	6	1	Blocos e Classes				
	09-Sep	1		AI-06 - Lista de Exercícios	20%		
		1	Máquina de Estados				
		1					
	7	1	Casos de Uso				
	16-Sep	1		AI-07 - Lista de Exercícios	20%		
		1	Sequência				
		1					
	8	1	Integração dos pontos de vistas em um				
	23-Sep 1		Associação dos artefatos de SE com modelos	AI-08 - Resumo sobre	10%	AI-08 - Descrição e	100%
	ļļ	1	Análise Operacional	Ciclo de Vida de Modelos		Contorno do Problema.	
	Ļ	1		,			
					100%		100%
	SEM						
	30-Sep						

		SEMAN	A	TEORIA	INDIVIDUAL	PESO	GRUPO	PESC
330-0-		9	1	Apresentação das necessidades				
		07-Oct	1	Intervenção Sistêmica			AG-09 - Apresentação	20%
			1	Associação com Requisitos			Necessidades	2070
			1					
		10	1	Apresentação da Arq e Req de sistema				
		14-Oct	1	Conceitos de Arquitetura Funcional	AI-10 - Exercícios de	20%	AG-10- Apresentação Arq	20%
				Arquitetura Conceitual	Arquitetura Funcional	20 /0	/ Caixa Preta	20%
			1					
		11	1	Utilização de modelos para outros processos				
	1	21-0 *	1				AG-11 - Geração de	10%
			1	Exportação automática de documentos			documentos	10 /8
			1					
		12	1	Apresentação da arquitetura Conceitual				
		28-Oct		Co-Engineering / CDF / RCE	AI-12 - Explorer RCE lendo	200/	AG-12 - Apresentação Arq. Conceitual e Proposta de VV	20%
			1	Arquitetura Concreta	arquivo do Capella	20%		
			1					
		13		* (ADS-HLG)				
		04-Nov			AG.13 - Explorar Plugin	000/		
					M2DOC (extra)	20%		
	V	14		* (ADS-HLG)				
	Λ	11-Nov			AG-14 - Explorar Plug in	000/		
					P4C (extra)	20%		
		15	1	Metamodelo				
		18-Nov		Capella Studio - Orizção de plugins	AG=5 - Figura do	0.004	AG-15 = Relatório de	
			1		Metamodelo	20%	Proposta de plugin	20%
			1					
		16	1	Apresentação final				
		25-Nov					AG-16 - Apresentação do	
		23-1100	1				Projeto Completo	20%
			-	Encerramento do Curso				
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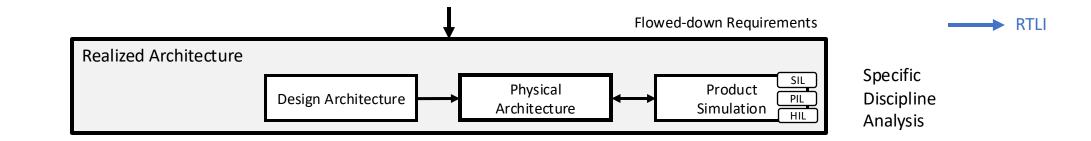


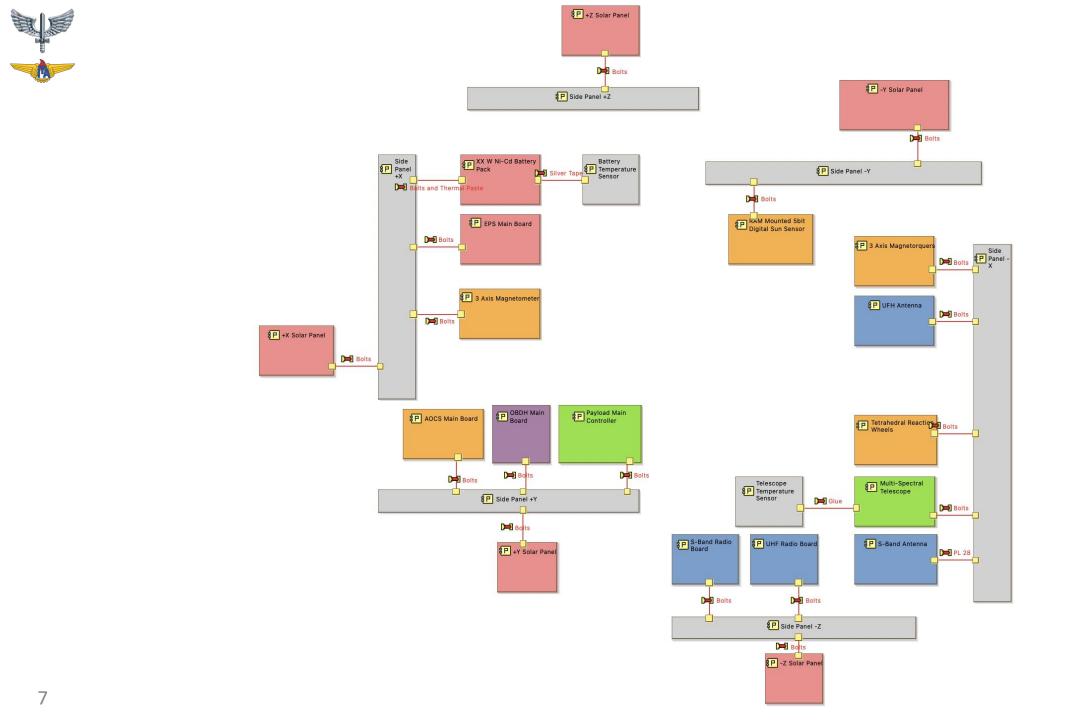


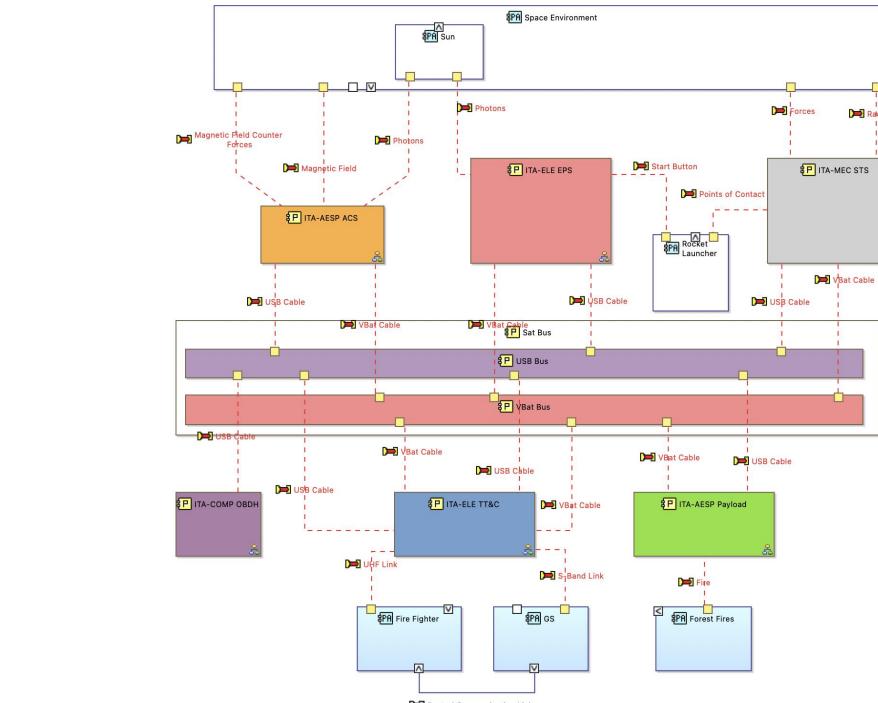


Example



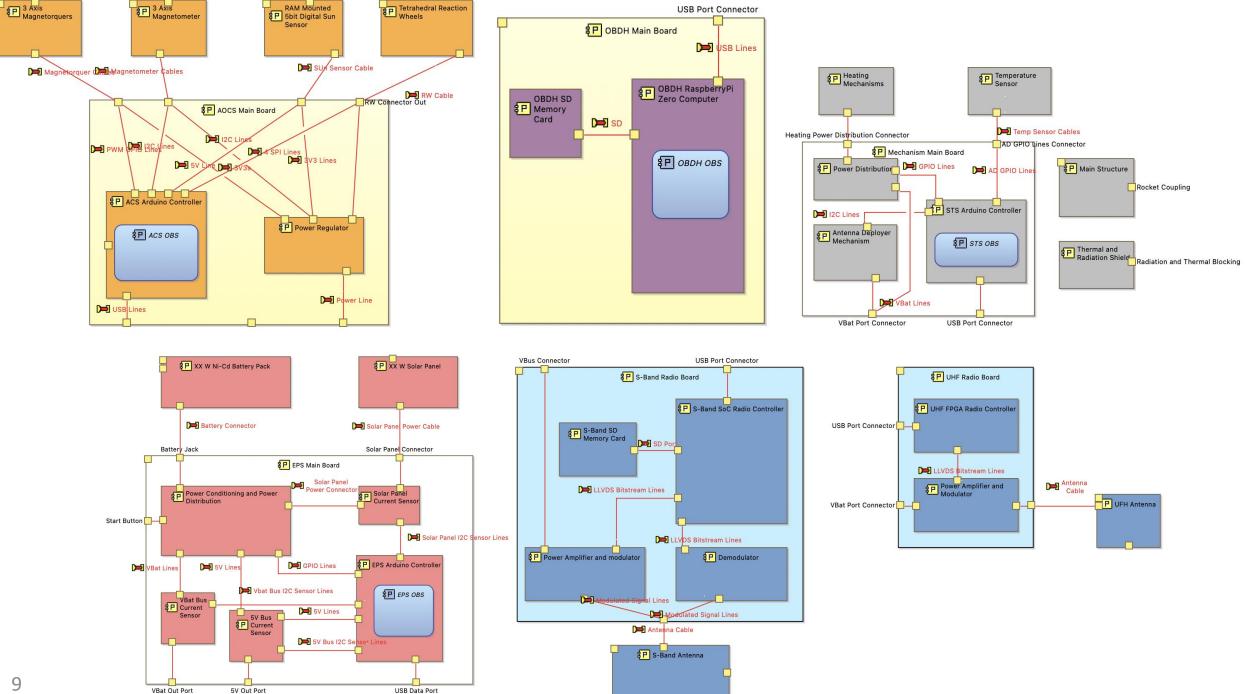






Radiation

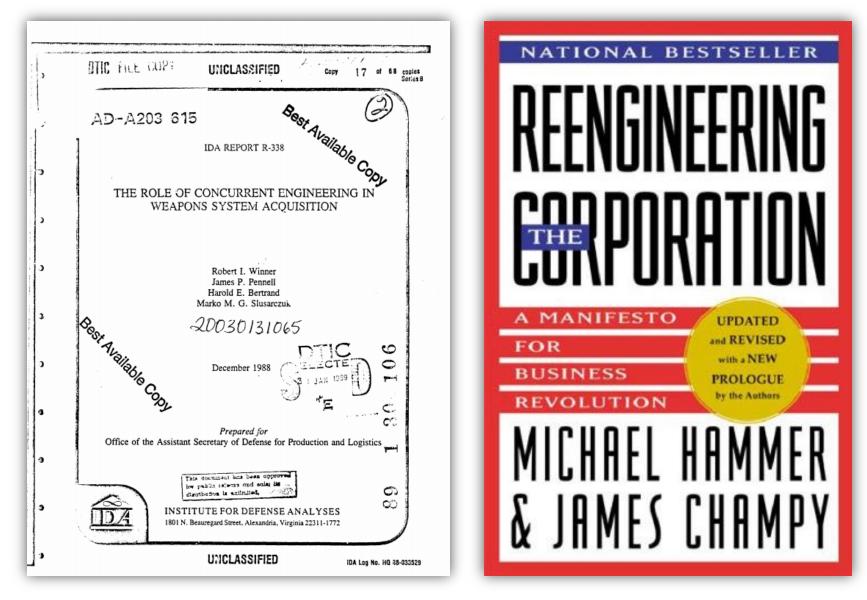
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Concurrent Engineering

Things started to speed-up



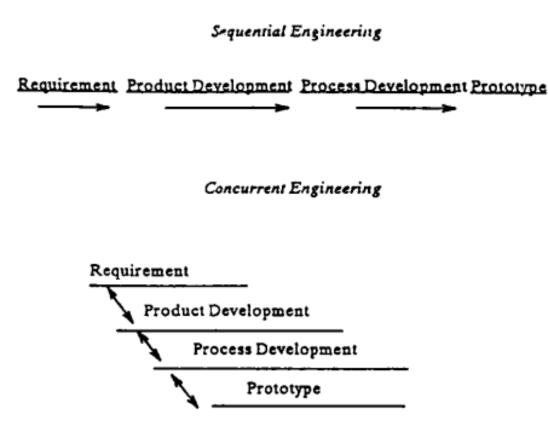
Participants at the first IDA concurrent engineering workshop discussed concurrent engineering practices in several U.S. companies. They described the use of methods that included traditional system engineering practices and new engineering and management approaches. DoD and Air Force initiatives to improve the acquisition process were also presented. Based on the discussion at that workshop, on further contributions from participants, and consultation with various reviewers, the following definition was developed:

> Concurrent engineering is a systematic approach to the integrated, concurrent design of products and their related processes, including manufacture and support. This approach is intended to cause the developers, from the outset, to consider all elements of the product life cycle from conception through disposal, including quality, cost, schedule, and user requirements.



Winner, Robert I., Pennell, James P., Bertrand, Harold E., and Slusarczuk, Marko M. G. (1991). "<u>The Role of Concurrent Engineering in Weapons System Acquisition</u>", *Institute for Defense Analyses Report R-338*, December 1988, p v.

Parallelization/INTEGRATION of work



<u>Concurrent engineering: an overview for Autotestcon | IEEE Conference Publication |</u> <u>IEEE Xplore</u>

The Role of Reduced Latency in Integrated Concurrent Engineering | Center for Integrated Facility Engineering (stanford.edu)

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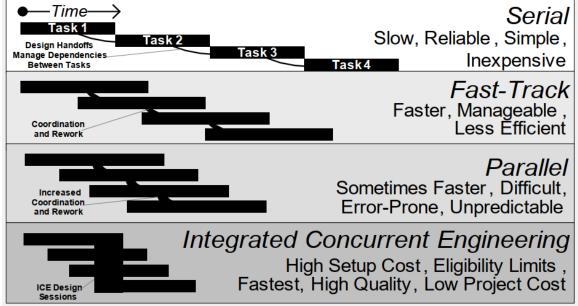


Figure 3: Degrees of Parallelism ICE radically increases task parallelism and operates to facilitate effective and efficient coordination with little waiting and rework. This diagram shows a schematic Gantt bar chart with four tasks arranged with increasing parallelism. Projects under increasing pressure to meet tight schedules often overlap tasks that once executed serially. Compressing schedule in this way is costly, difficult, and risky for teams failing to anticipate the complex interactions between product, organization, process, and technology. Many industries are broadly parallelizing design tasks, but few teams have experimented with ICE yet. ICE represents the most accelerated of these engineering methods, in which the full organization gathers and executes the most interdependent work together. We predict and observe in ICE that the coordination and rework effort equals or exceeds the effort given to direct work. ICE works well when the individual subtask durations are short (a few minutes) and coordination latency is reliably exceptionally short (waits to initiate discussion rarely exceed one minute), and coordination duration is short (a few minutes at most).

2001 – Agile manifesto

Manifesto for Agile Software Development

We are uncovering better ways of developing software by doing it and helping others do it. Through this work we have come to value:

Individuals and interactions over processes and tools Working software over comprehensive documentation Customer collaboration over contract negotiation Responding to change over following a plan

> That is, while there is value in the items on the right, we value the items on the left more.

> > Ron Jeffries

Jon Kern

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in its entirety through this notic

James Grenning Kent Beck Mike Beedle Jim Highsmith Arie van Bennekum Andrew Hunt Alistair Cockburn Ward Cunningham Martin Fowler Brian Marick

Robert C. Martin Steve Mellor Ken Schwaber Jeff Sutherland Dave Thomas

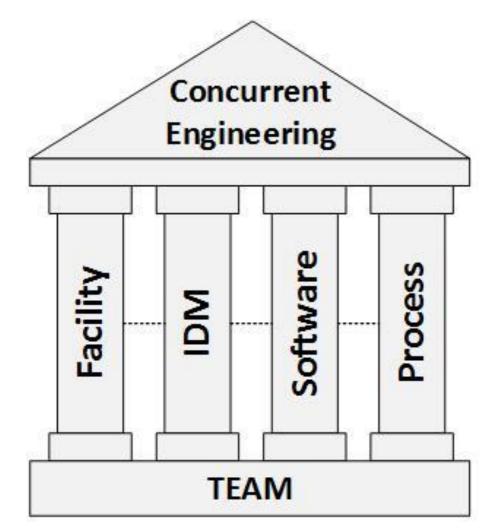
• We follow these principles:

- Our highest priority is to satisfy the customer through early and continuous delivery of valuable software.
- Welcome changing requirements, even late in development. Agile • processes harness change for the customer's competitive advantage.
- Deliver working software frequently, from a couple of weeks to a couple of months, with a preference to the shorter timescale.
- Businesspeople and developers must work together daily throughout the project.
- Build projects around motivated individuals. Give them the environment and support they need and trust them to get the job done.
- The most efficient and effective method of conveying information to and within a development team is face-to-face conversation.
- Working software is the primary measure of progress.
- Agile processes promote sustainable development. The sponsors, developers, and users should be able to maintain a constant pace indefinitely.
- Continuous attention to technical excellence and good design ٠ enhances agility.
- Simplicity--the art of maximizing the amount of work not done--is essential.
- The best architectures, requirements, and designs emerge from self-• organizing teams.
- At regular intervals, the team reflects on how to become more effective, then tunes and adjusts its behavior accordingly.

Manifesto for Agile Software Development (agilemanifesto.org)

14

Modern concurrent engineering



"Modern Concurrent Engineering"



Bidirectional Graphical Modelling Supporting Concurrent Spacecraft Design | Semantic Scholar

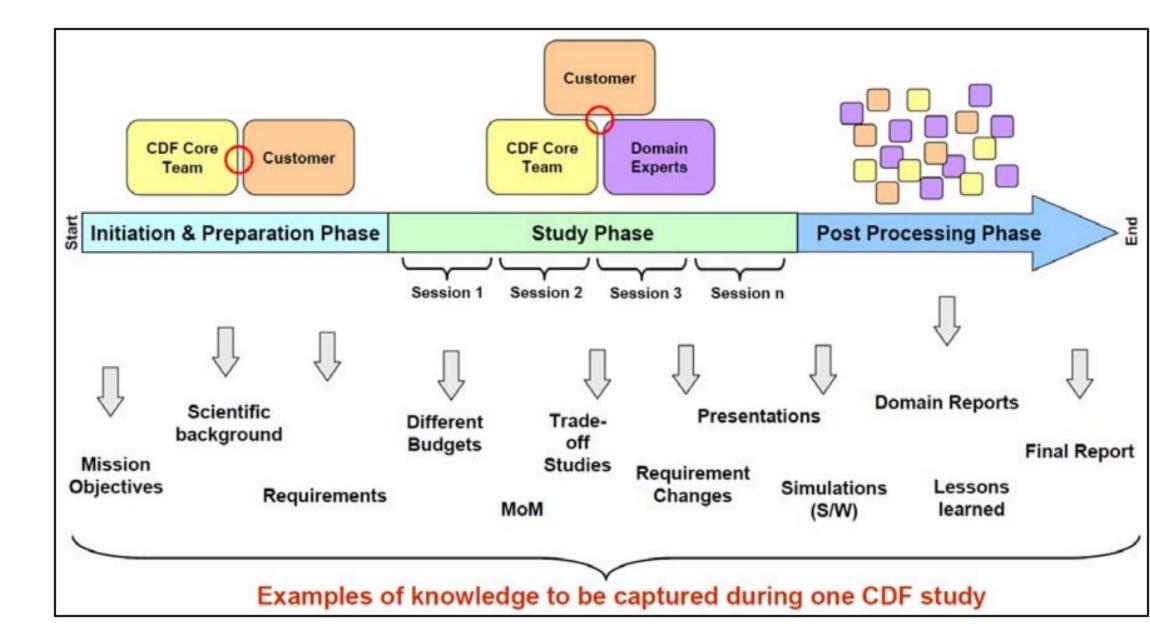
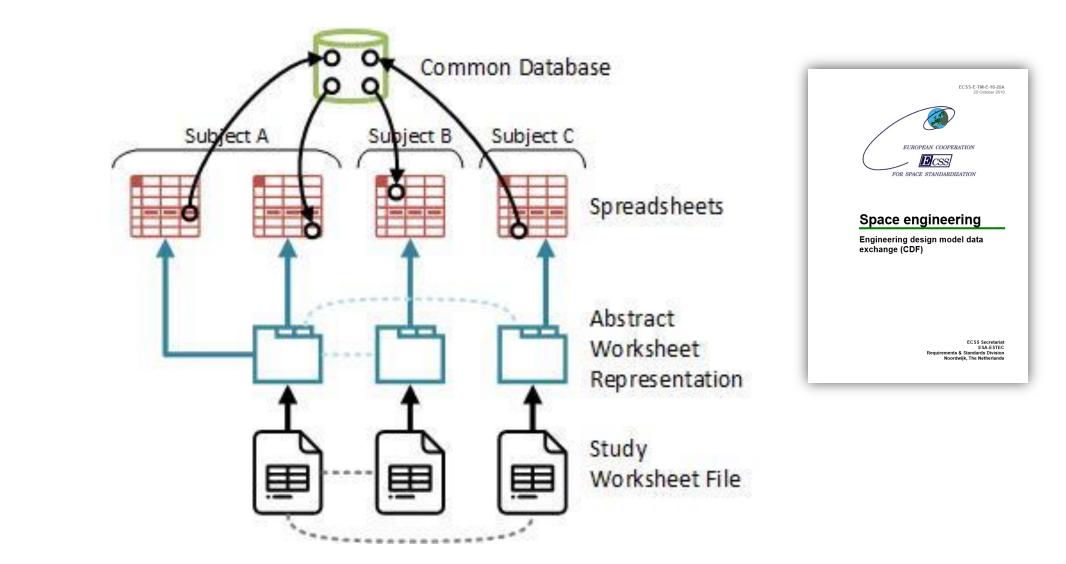


Figure 2: Concurrent Engineering Process with respect to Knowledge Management



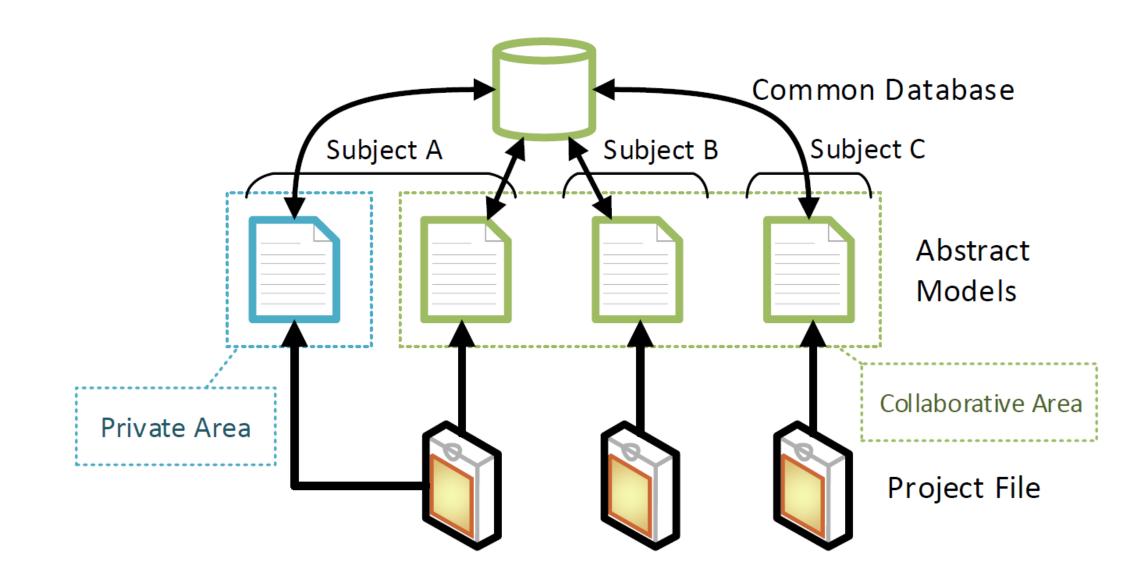
Multiple spreadsheet through a shared bd

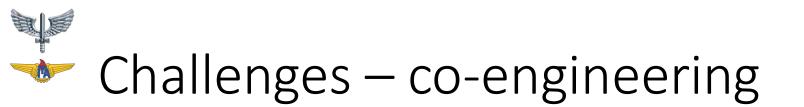








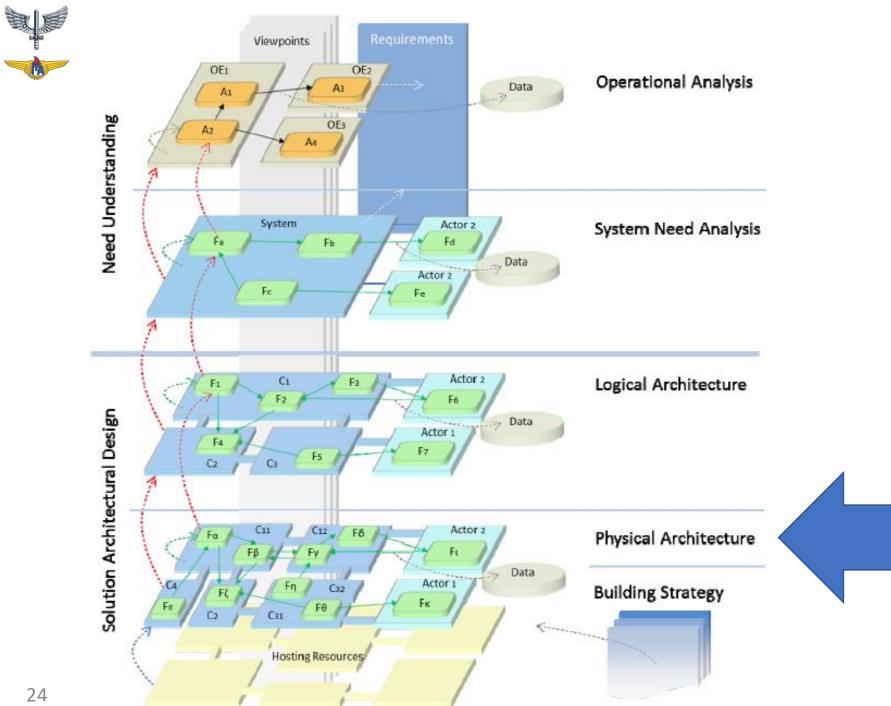




- Collaborative work (SystemToSubsystem / T4C)
- Data-base of solutions (reuse) (Libraries)
- Strong Interface Definition/Management
- Optimization (man-made / automatic)
- Coupled analysis Simulation (P4C and other connectors)
- Model has SEVERAL THOUSANDS of advantages, however the spreadsheet metaphor is easy and known.



PHYSICAL ARCHITECTURE



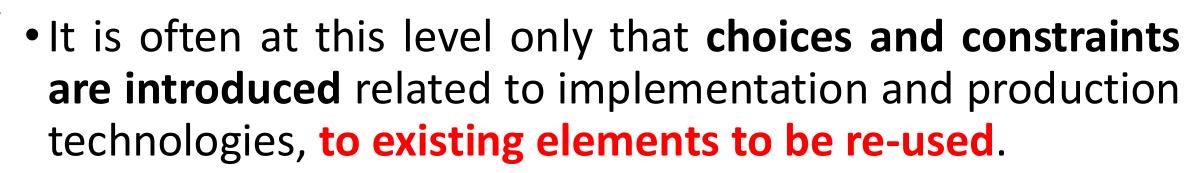


WHAT IS IN THE PHYSICAL ARCHITECTURE (PA)?



"how the system will be built"

- This perspective has the same objective as the logical architecture, except that it defines the finalized architecture of the system, as it should be completed and integrated. It adds the functions required by the implementation and technical choices and reveals the behavioral components that perform these functions. These behavioral components are then implemented using host implementation components that offer them the necessary material resource.
- Defines the solution at a <u>sufficient level of detail to specify the</u> <u>developments and acquisitions of all subsystems (or components)</u> <u>to be implemented</u>, and to define and orientate the system integration, verification and validation (IVV) phases.



- Any ambiguities or inaccuracies that could still exist in the logical architecture (LA), if they did not impact its structuring, should this time be resolved, in order to constitute clear development contracts for the identified components.
- PA is the **privileged place of co-engineering** with subsystem engineering and software or hardware components.

The main activities to be undertaken for the definition of the finalized PA

- to define the structuring principles of the architecture and behavior;
- to detail and finalize the expected system behavior;
- to build and rationalize one or more possible system architectures;
- to select, complete and justify the system architecture retained.

Definition of the structuring principles of the architecture and behavior

- The major objective of the PA is to **minimize complexity through rationalizing**.
 - One of the most used means of rationalization consists of reducing diversity and heterogeneity within the solution, by searching for similarities and therefore possible architecture invariants (sometimes called "patterns") that can be applied more than once in the same manner – or configurable.
 - Another classic way to overcome complexity is based on the **separation of concerns and their containment** within parts of the architecture as separate as possible from each other.

Detail and finalization of the expected system behavior

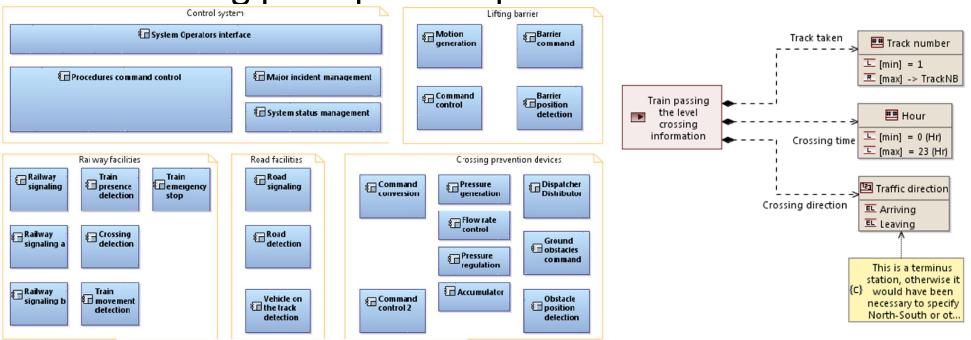
• Define the expected behavior of the system, to a level of detail and validation enough so that each of its components can be implemented (or selected and purchased), without any further risk or major questioning; this definition must of course demonstrate compliance with constraints, especially nonfunctional constraints, by which the system will have to abide when being used under operational conditions.

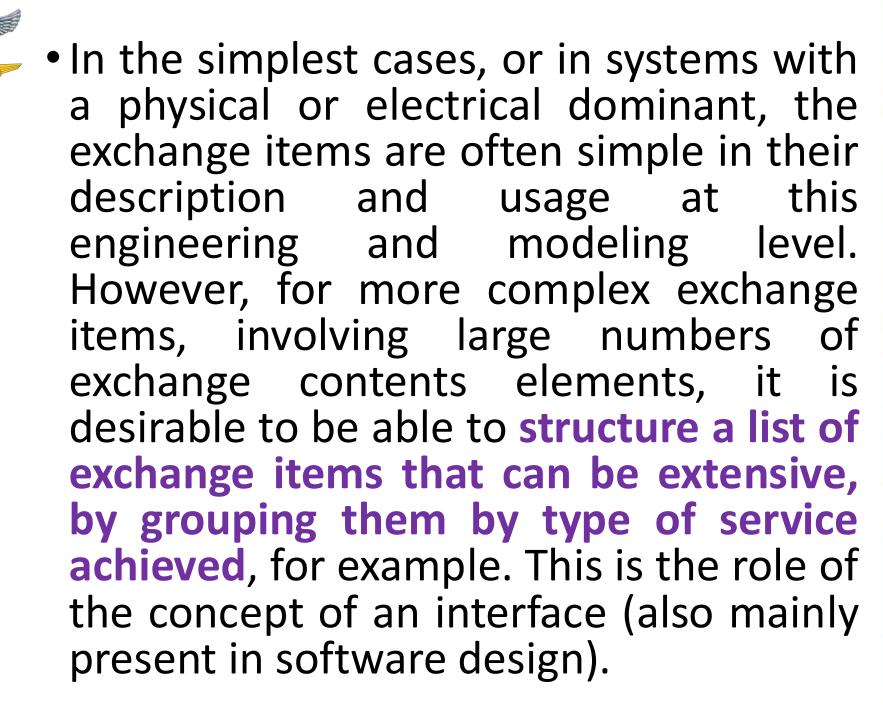


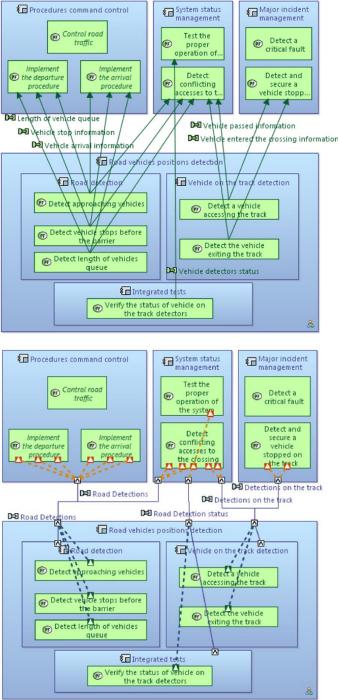
 In particular, the finalized behavior should not necessarily be considered as a simple refinement of that defined in the LA. The finalization of the chosen behavior in fact often constitutes a re-designing, which must result from the comparison between the principle behavior of the LA, and the implications of the principles chosen in the PA: technological choices and adoption of standards, previous structuring principles, etc.

Construction and rationalization of one or more possible system architectures

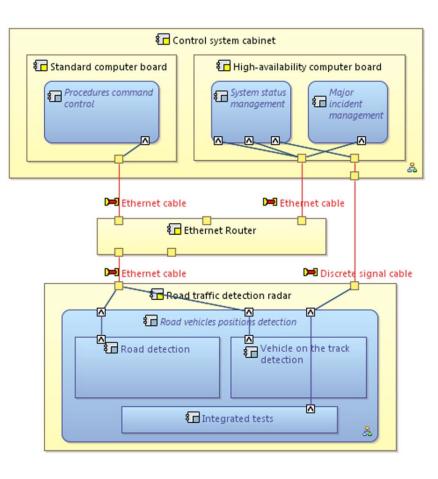
• This step is intended to **define one or more solutions reflecting the structuring principles** defined in the LA, the previous finalized behavior, satisfying the expected non-functional constraints and applying technology and reuse choices decided in accordance with the structuring principles adopted.







- The PA complements this behavioral description by way of the definition of implementation components, or hosting physical components, containing behavioral components and forming the infrastructure of the system; the behavioral components are deployed on these host components, which provide necessary resources for their behavior and hardware vectors (links) for their communications. It may thus consist of highperformance computers, resources for digital or analog processing, mechanical systems, evaporators, furnaces, chemical reactors, etc.
- Hosting physical components are themselves connected by physical links, reflecting the media that channel exchanges between behavioral components (a cabled network, a satellite link, a pipe or a mechanical shaft, for example).
- The same rationalization processes have to be performed for hosting physical components as for the behavior and behavioral components, in compliance with the established structuring principles.

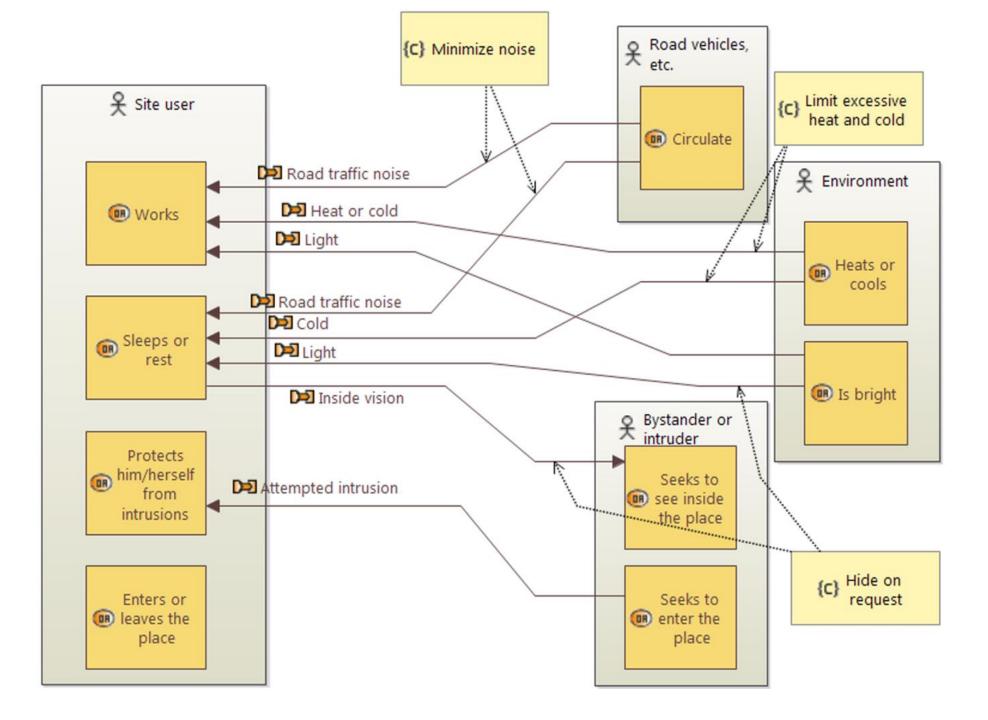


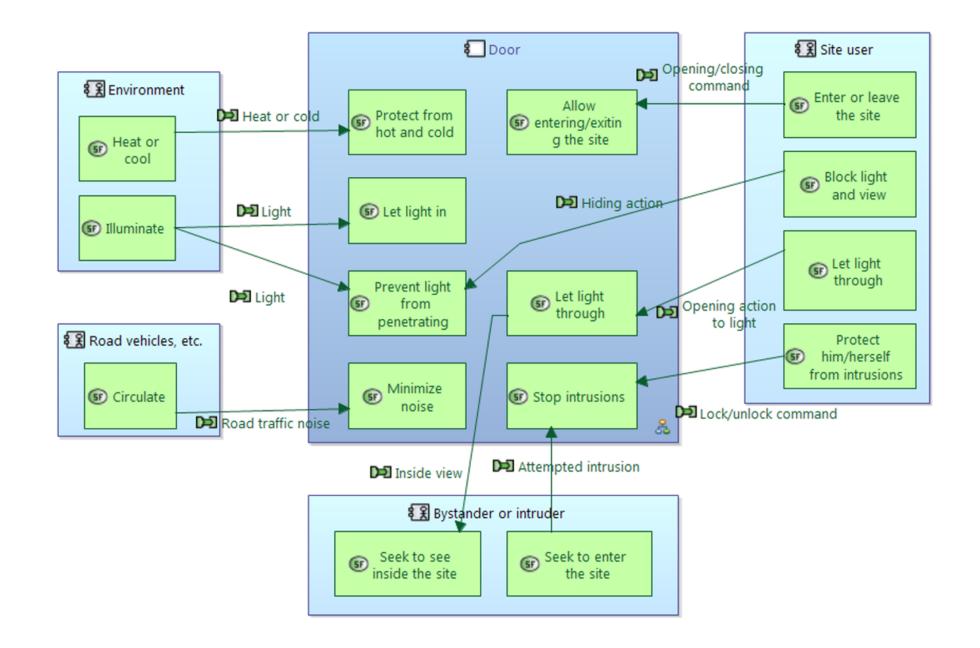
Selection, completion and justification of the system architecture

- Finalize the choices among potential alternatives, and verify that the retained alternative satisfies, possibly by means of an acceptable trade-off, all of the needs and constraints that have been imposed thereon.
- For example, the implementation resources available may not be sufficient to support an expected behavior or associated properties (computational load too high for a given process in computers supporting it, temperature and pressure too high for a given pipe, etc.). This will lead to a redesigning of the architecture, including a redecomposition and a different distribution of behavioral components, or the use of other implementation resources (more powerful computers, more robust pipes).

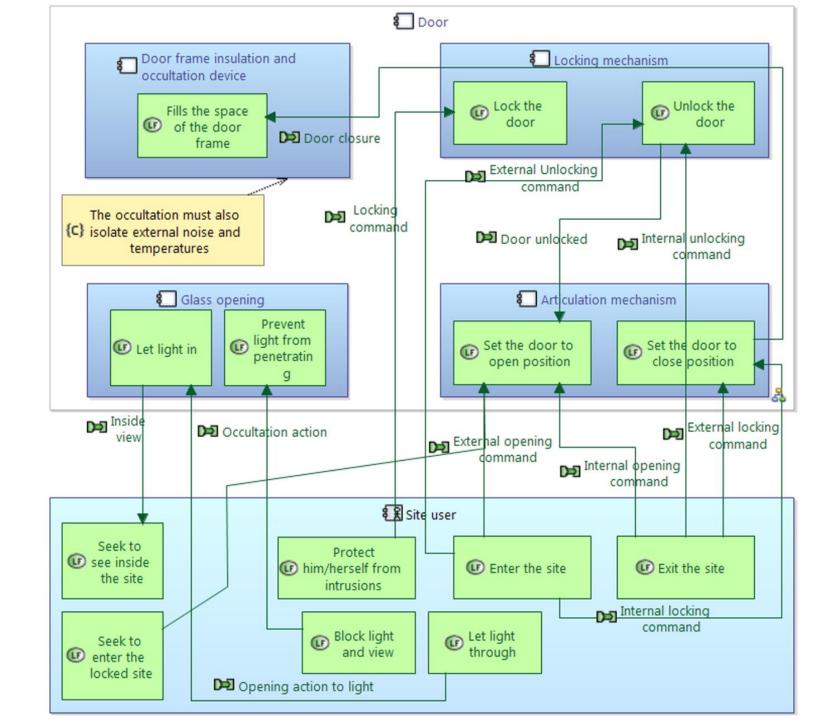


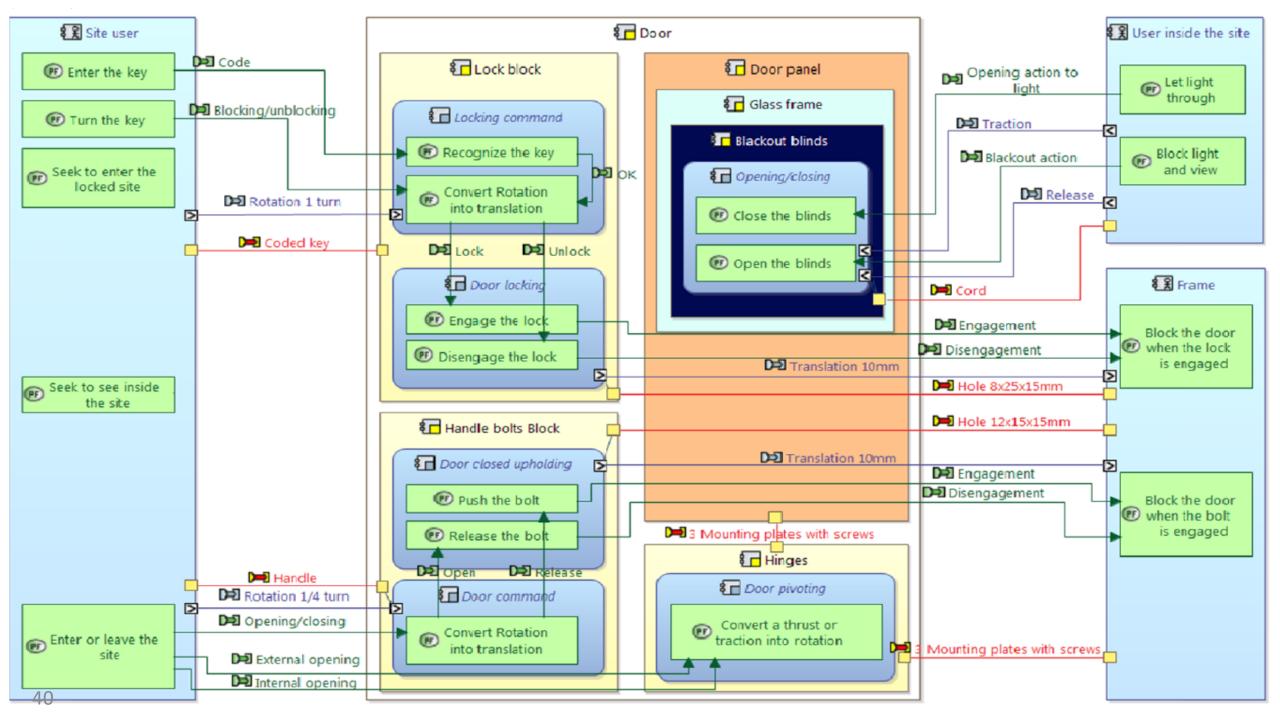
define the structuring principles of the architecture and behavior;	Factors impacting or constraining the definition of the architecture, as well as the viewpoints and structuring design choices mentioned earlier, equally apply to this level of architecture and are to be taken into account in a similar way.
detail and finalize the	define the expected behavior of the system, to a level of detail and validation
expected system	enough so that each of its components can be implemented (or selected and
behavior;	purchased), without any further risk or major questioning
build and rationalize one or more possible system architectures	define one or more solutions reflecting the structuring principles defined in the LA, the previous finalized behavior, satisfying the expected non-functional constraints and applying technology and reuse choices decided in accordance with the structuring principles adopted.
select, complete and	finalize the choices among potential alternatives, and verify that the retained
justify the system	alternative satisfies, possibly by means of an acceptable trade-off, all of the
architecture retained.	needs and constraints that have been imposed thereon.











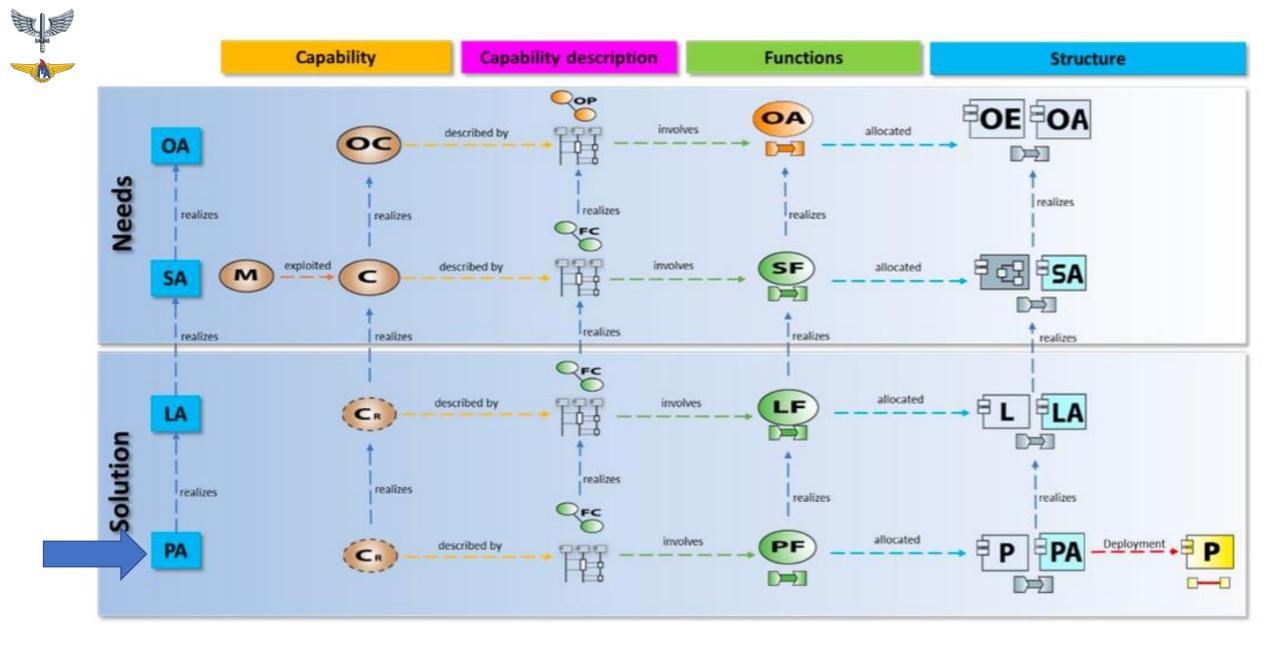


Figure 2.3: Arcadia ontology traceability

https://www.slideshare.net/HelderCastro3/mbse-with-arcadia-methodpdf-256664096

Arcadia layer	Requirements	Capability	Capability description	Functional	Structure	Modes and States	Data	Inter
	R-OA	OA1	OA2	OA3	OA4	M&S-OA5	D-OA6	I-C
Operational Analysis	Capture stakeholder requirements	Define Operational Capabilities	Define processes and scenarios	Define Operational Activities and interactions	Capture Operational Entities and Actors. Allocate Operational Activities to Operational Actors, Entities	Define operational modes and states	Define operational data model	Define inter describe int scenarios
, ,	UR FR	oc				MS	•	
	R-SA	SA1	SA2	SA3	SA4	M&S-SA5	D-SA6	I-
System Analysis	Derive Stakeholder requirements and capture System	Define System Missions and System Capabilities	Define Functional Chains and Scenarios.	Define System Functions. Define Functional Exchanges and components	Allocate System Functions to System and Actors	Define system modes and states	Define system data model	Define inte describe in scenarios
	requirements	MC	Crc	SF 🕞	for fsa	MS	•	Enrich Logi
	R-LA	LA1	LA2	LA3	LA4	M&S-LA5	D-LA6	ŀ
Logical Architecture	Derive system requirements and Capture components requirements	Transition Capabilities Realization from system layer	Define Functional Chains and scenarios	Derive System Functions and define Logical Functions. Define Functional Exchanges and components.	Allocate Logical Functions to Logical Components	Define logical components modes and states	Define logical data model	Delegate S Interfaces Logical Inte Enrich Log
	UR FR	CR				MS	• • • • •	0
	R-PA	PA1	PA2	PA3	PA4	M&S-PA5	D-PA6	I-
Physical Architecture	Derive logical requirements and capture physical requirements	Transition Capabilities Realization from logical layer	Define Functional Chains, Scenarios, and Physical Path	Derive Logical Functions and define Physical Functions. Define Functional Exchanges and components.	Define Physical Nodes and refine Behavioural Physical Components. Allocate Behavioural Components.	Define physical nodes modes and states	Define physical data model	Delegate Lo Interfaces Physical Int Enrich Phys Scenarios.
	UR FR	CR		PF) 🚬	E P	MS	•	

Table 3.2: Arcadia matrix activities

https://www.slideshare.net/HelderCastro3/mbse-with-arcadia-methodpdf-256664096

Arcadia layer	Requirements	Capability	Capability description	Functional	Structural	Modes and States	Data	Interfaces
Operational Analysis	R-OA No dedicated diagram	OA1 [OCB] Operational Capabilities	OA2 [OAS] Operational Activity Scenario [OPD] Operational Process Scenario [OES] Operational Entity Scenario	OA3 [OABD] Operational Activity Breakdown Diagram [OAIB] Operational Activity Interaction Blank	OA4 [OEBD] Operational Entities Blank Diagram [ORB] Operational Roles Blank [OAB] Operational Architecture Blank	M&S-OA5 [MSM] Modes and States	D-OA6 [CDB] Class Diagram	I-OA7 [IDB] Interface Definition Blank [CEI] Component External Interfaces [IS] Interface Scenario [CDI] Component Detailed Interface
System Analysis	R-SA No dedicated diagram	SA1 [MCB] Mission and Capabilities Blank [CC] Contextual Capability	SA2 [FS] System Functional Scenario [ES] System Entity Scenario [SFCD] System Functional Chain Description	SA3 [SFBD] System Functional Breakdown Diagram [SDFB] System Data Flow Blank	SA4 [CSA] Contextual System Actor [SAB] System Architecture Blank	M&S-SA5 [MSM] Modes and States	D-SA6 [CDB] Class Diagram	I-SA7 [IDB] Interface Definition Blank [CEI] Component External Interfaces [IS] Interface Scenario [CDI] Component Detailed Interface
Logical Architecture	R-LA No dedicated diagram	LA1 [CRB] Capabilities Realization Blank [CRI] Contextual Capability Realization Involvement	LA2 [FS] Logical Functional Scenario [ES] Logical Entity Scenario [LFCD] Logical Functional Chain Description	LA3 [LFBD] Logical Functional Breakdown Diagram [LDFB] Logical Data Flow Blank	LA4 [LCBD] Logical Component Breakdown Diagram [LAB] Logical Architecture Blank	M&S-LA5 [MSM] Modes and States	D-LA6 [CDB] Class Diagram	I-LA7 [IDB] Interface Definition Blank [CEI] Component Externa Interfaces [IS] Interface Scenario [CDI] Component Detaile Interface
Physical Architecture	R-PA No dedicated diagram	PA1 [CRB] Capabilities Realization Blank [CRI] Contextual Capability Realization Involvement	PA2 [FS] Physical Functional Scenario [ES] Physical Entity Scenario [PFCD] Physical Functional Chain Description	PA3 [PFBD] Physical Functional Breakdown Diagram [PDFB] Physical Data Flow Blank	PA4 [PCBD] Physical Component Breakdown Diagram [PAB] Physical Architecture Blank	M&S-PA5 [MSM] Modes and States	D-PA6 [CDB] Class Diagram	I-PA7 [IDB] Interface Definition Blank [CEI] Component Externa Interfaces [IS] Interface Scenario [CDI] Component Detailed Interface

Table 3.3: Arcadia diagrams matrix



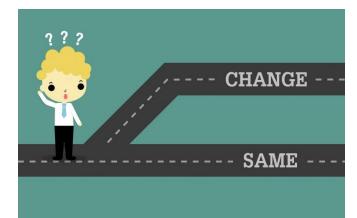
PHYSICAL ARCHITECTURE CONCEPTS



 At this level, the main concepts proposed by Arcadia are similar to those of the Logical Architecture: Physical Function, Functional Exchange, Physical Component, Physical Actor, etc. However, there are some additional concepts, notably:



• Behavior Physical Component: Physical Component tasked with Physical Functions and therefore carrying out part of the behavior of the System (for example software component, data server, etc.);

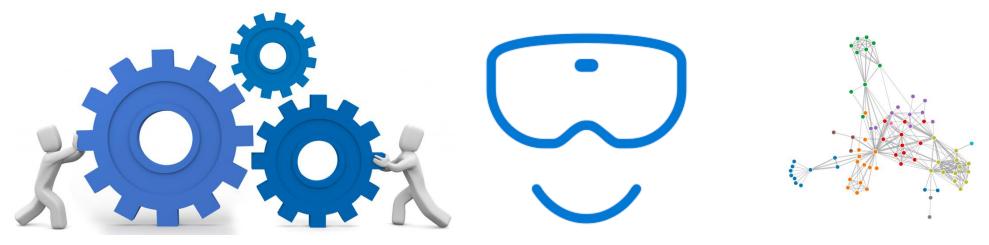






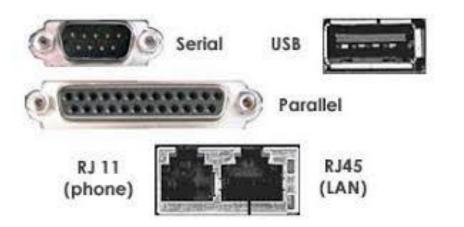


 Node (or Implementation) Physical Component: Physical Component that provides the material resources needed for one or several Behavior Components (for example processor, router, OS, etc.).





• Physical Port: non-oriented port that belongs to an Implementation Component (or Node). The structural port (Component Port), on the other hand, has to belong to a Behavior Component;

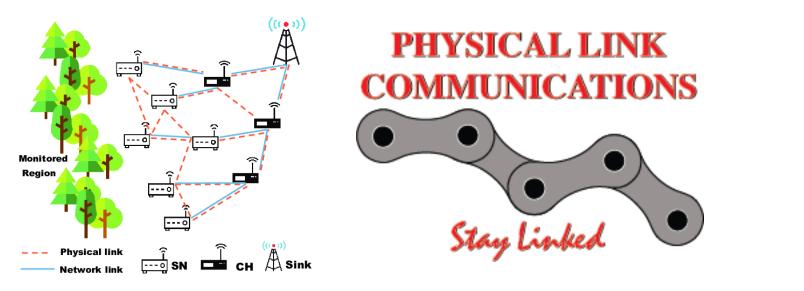








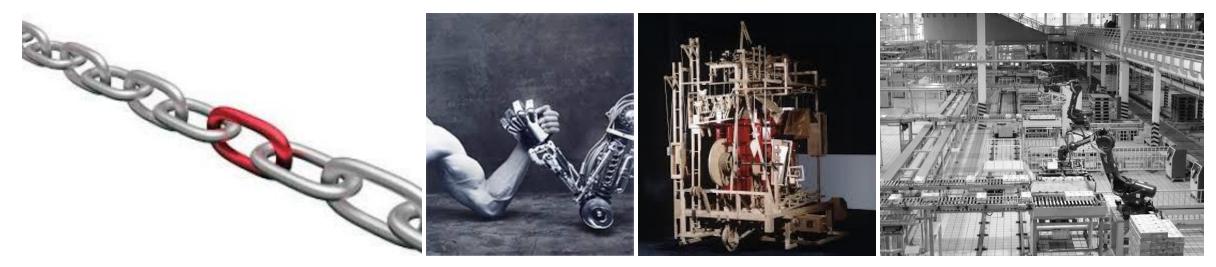
• Physical Link: non-oriented material connection between Implementation Components (or Nodes). The Component Exchange remains a connection between Behavior Components. A Physical Link allows one or several Component Exchanges to take place (for example Ethernet cable, USB cable, etc.);

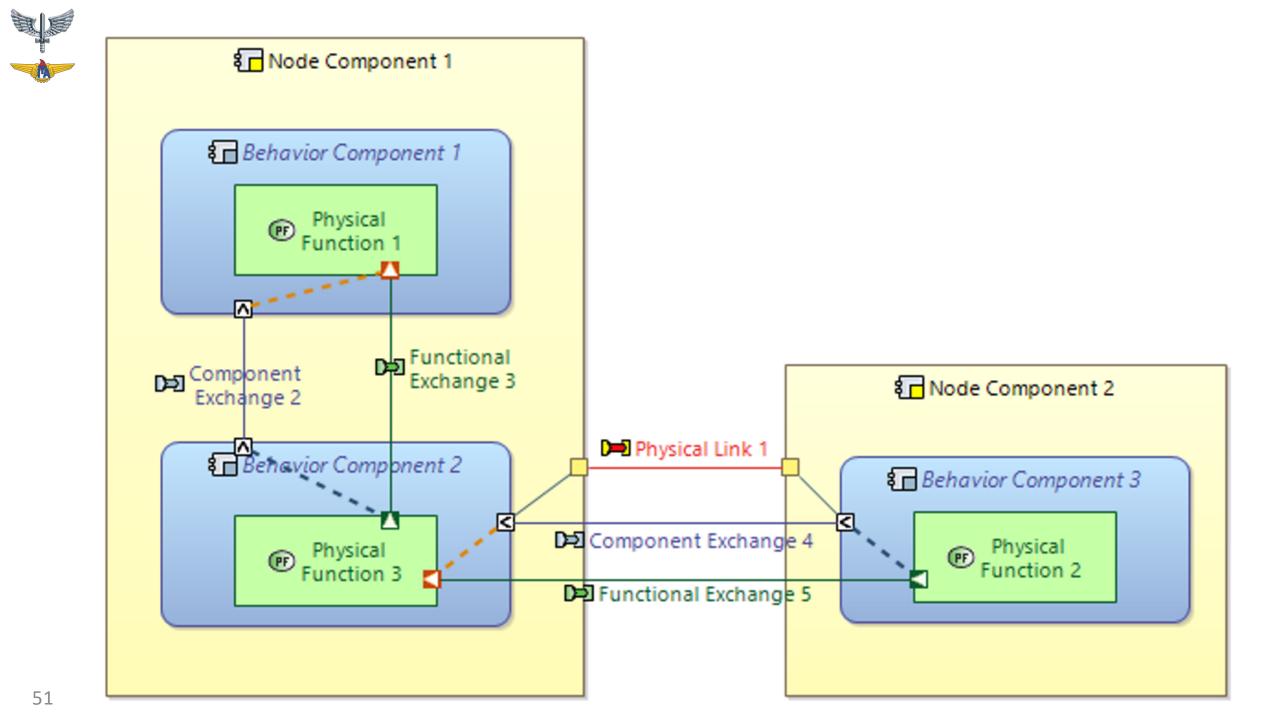






• Physical Path: organized succession of Physical Links enabling a Component Exchange to go through several Implementation Components (or Nodes).







PHYSICAL ARCHITECTURE DIAGRAMS



Transition from Logical Functions



Perform an automated transition of Logical Functions



Create Traceability Matrix

Refine Physical Functions, describe Functional Exchanges





[PDFB] Create a new Functional Dataflow Blank diagram



[FS] Create a new Functional Scenario

Define Physical Components and Actors, Manage deployments



Perform an automated transition of External Logical Actors



Perform an automated transition of Logical System



[PAB] Create a new Physical Architecture diagram

Initialization and automated update of the physical functions according to the logical functions

The transition tools create a first 1-1 traceability mapping between Physical Architecture and Logical Architecture. Use dedicated traceability matrices to modify the traceability relationships.

Enrich and details the functional breakdown with new physical functions.

Describe the data flows between physical functions and identify specific functional chains.

The initialization and automated updated of the physical actors can be automatically performed according to logical actors.

Define the physical components. A physical component is a physical representation of an entity in the system (hardware, software, firmware, personnel, facilities, data, materials, services and processes). It is in charge of the implementation of one or several logical components. A physical component can be Node or Behavior.

	The behavioral physical components are responsible for implementing the physical functions. Manage these allocations using an architecture diagram and deduce component exchanges implementing the functional exchanges.		
✓ Allocate Physical Functions to Physical Components	Manage the deployment of behavior components on node		
년 = [PAB] Create a new Physical Architecture diagram	components and deduce physical links and paths. Create dataflow scenarios to illustrate functional exchanges between the components		
IES] Create a new Exchange Scenario			
Create a new allocation Physical Component / Physical Function Matrix			
 Delegate Logical Interfaces and create Physical Interfaces 	Delegate each logical interface to one physical component. Create new physical interfaces between components.		
[CII] Create a new Contextual Internal Interface diagram on the Physical Syste	<u>m</u>		

Perform an automated transition of Logical Architecture Capabilities

[IS] Create a new Interface Scenario

Specify the dynamical behavior of the physical components by completing the interaction sequences coming from the Logical Architecture. The enrichment of the interaction sequences and the identification of the new physical interfaces are two very tight and iterative activities.

The scenario refinement process is iterative, each update on a source can be automatically propagated to the target.

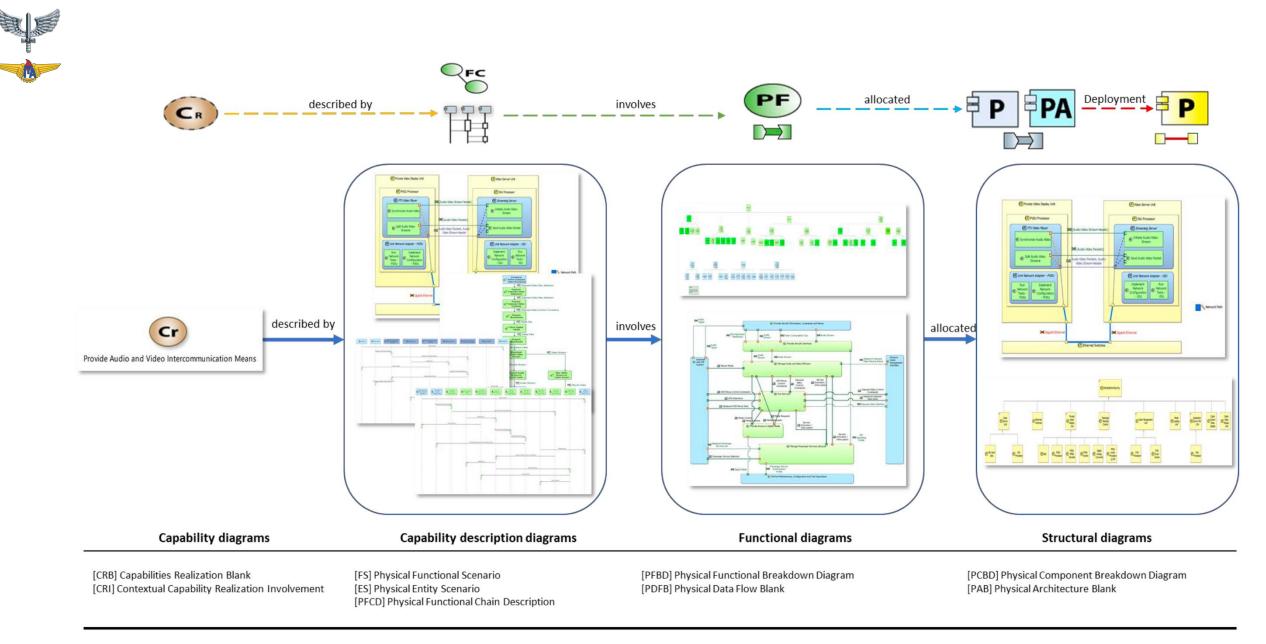


Figure 7.7: Physical Architecture traceability flow



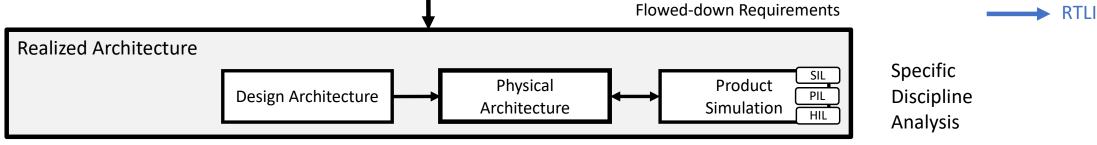
Final Considerations



- Physical architecture answers:
 - "how the system will be built"
- In the physical architecture the system choices are concretized.
- Focus on technological trades that implements the functions
- Focus in the realize the "to-be"
- Maps the technologies into the designed functions.

Atividades para a próxima aula

- Fazer a etapa da formalização do sistema construído
- Apresentar como o sistema logístico vai ser construído.
- Apresentar o modelo da arquitetura final:
 - Características mínimas: realizar 2 nós com 1 comportamento em cada (mínimo). Anexar os comportamentos vindos da LA. Indicar como o sistema foi "totalmente construído / entregue pelo fabricante".
- Extra-fun: Gerar um doc com no mínimo uma arquitetura de cada camada (AO-PA), trazer o título do diagrama e o diagrama automaticamente.





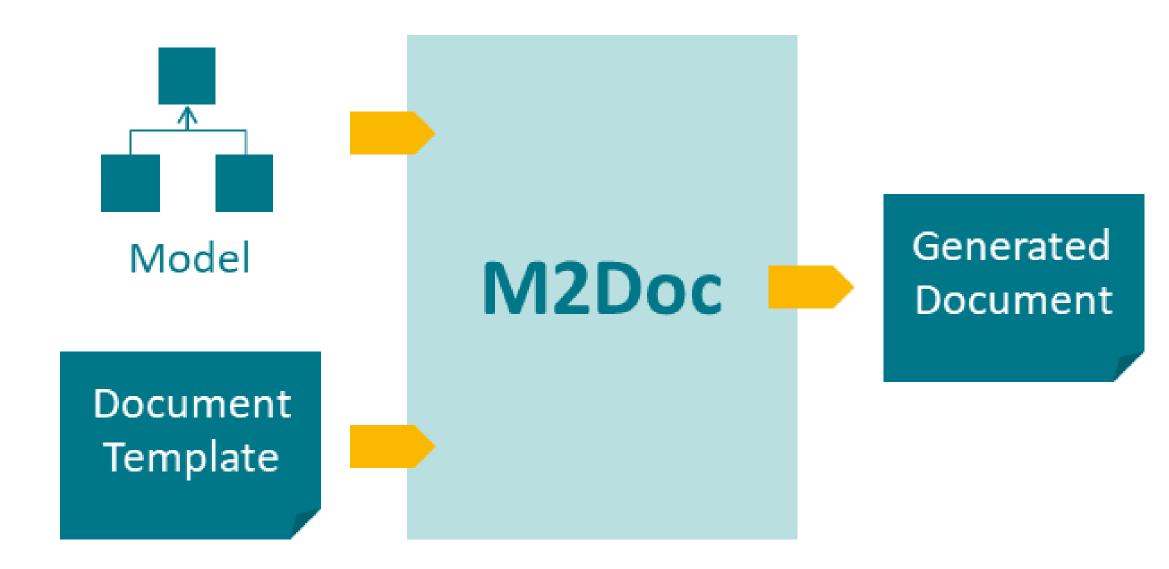
Document Generation

https://www.m2doc.org/



- O projeto M2Doc fornece a geração de documentos do Word (arquivos .docx) com base em um modelo de documento e modelos EMF.
- A abordagem geral consiste na criação de modelos no formato OOXML em que a criação de texto estático se beneficia dos recursos WYSIWYG do Microsoft Word. Partes dinâmicas são inseridas usando um vocabulário dedicado de código de campos OOXML.
- Os campos são usados principalmente para inserir números de página, referências, etc. O M2Doc faz uso de diretivas de geração de documentação. Isso permite uma separação total entre o documento e as diretivas M2Doc.







nysical Model Data Diction	Idly		[m:db.name]
<u>bles</u> ¶			
2 Tables au niveau du			
(m:for table db.allTable			
.2.1 <u>Table· (m:table.nan</u> .2.1.1 <u>Table· (m:table.na</u>	nen mail description¶		
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SGDB¤	m:db.DBLibrary()		
Record-number¤	m:table.recordNumber()		
Record-numbers	in table. recordivatiber()}∞		
.2.1.2 (m:table.name)· c	olumns·list¶		
 →	Name¤	Type¤	
n:for·column· ·table.colu	umns		
(m:column.name)¤	umns)	[m:column.typeName()]#	
	umns}	(m:column.typeName()) ^µ	
[m:column.name]¤	<u>umns}</u> ¶	(m:column.typeName()) ^a	
(m:column.name) ¤ n:endfor•)¶ ::for-column-table.column:		· · · · · · · · · · · · · · · · · · ·	
<u>{m:column.name}</u> ¤ <u>n:endfor-}¶</u> n:for column table.column: 2.1.3 <u>Column {m:colu</u> rn:	nn.name <u>) from</u> table (m:table.r	· · · · · · · · · · · · · · · · · · ·	
<u>{m:column.name}</u> ¤ <u>n:endfor-}¶</u> n:for column table.column: 2.1.3 <u>Column {m:colu</u> rn:		· · · · · · · · · · · · · · · · · · ·	
<u>{m:column.name}</u> ¤ <u>n:endfor-}¶</u> n:for column table.column: 2.1.3 <u>Column {m:colu</u> rn:	nn.name}· from table· (m:table.r umn.name}· description¶	· · · · · · · · · · · · · · · · · · ·	
<u>{m:column.name</u> }¤ <u>n:endfor-}¶</u> ::for column table.column: 2.1.3 <u>Column {m:colu</u> r 2.1.3.1 <u>Column {m:colu</u> r	nn.name]· from table· (m:table.r umn.name]· description¶	name)¶	
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-----Saut de page ------¶

1ysical·Model·Data·Dictic bles¶	nary	→	serie-oracle
2 Tables au niveau du			
2.1 Table GS_SERIE			
2.1.1 Table GS_SERIE			
Name¤	GS_SERIE¤		
SGDB ¹²	physicalTypes¤		
Record number¤	10000¤		

1.2.1.2 GS_SERIE columns list

→ Name¤	Type¤	¤
GS_SERIE_ID#	INTEGER [¤]	¤
RF_GENRE_ID¤	INTEGER¤	¤
RF_PAYS_ID¤	INTEGER¤	¤
GS_SERIE_NOM¤	VARCHAR2 [#]	a
GS_SERIE_ANNEECRE	VARCHAR2 [#]	¤
GS_SERIE_ANNEEFIN¤	VARCHAR2 [#]	¤
GS_SERIE_DESCRIPTION=	VARCHAR2 [#]	¤
GS_SERIE_LOGO	VARCHAR2 ^µ	¤
GS_XTOPSUP#	VARCHAR2 [#]	¤
GS_XDMAJ [#]	DATE	¤

¶ 1.2.1.3 <u>Column·GS_SERIE_ID from table·GS_SERIE</u>¶ 1.2.1.3.1 <u>Column·GS_SERIE_ID description</u>¶

1.2.1.3.1 COMINIPOS_SERIE	
Nom¤	$GS_SERIE_ID \rightarrow \square$
Type∙de•données¤	INTEGER¤
<i>Obligatoire</i> ¤	Oui¤
Commentaire¤	PK-de la table GS_SERIE∝
Clé primaire¤	Non¤
Clé étrangère¤	Oui¤
Nombre d'enregistrements¤	5000¤
1.2.1.4 Column RF_GENRE	ID from table GS_SERIE¶
1.2.1.4.1 Column RF_GENR	E_ID-description¶

Nom¤	RF_GENRE_ID	-+	a	¤
Type∙de•données¤	INTEGER¤			¤
Obligatoire¤	Oui¤			α

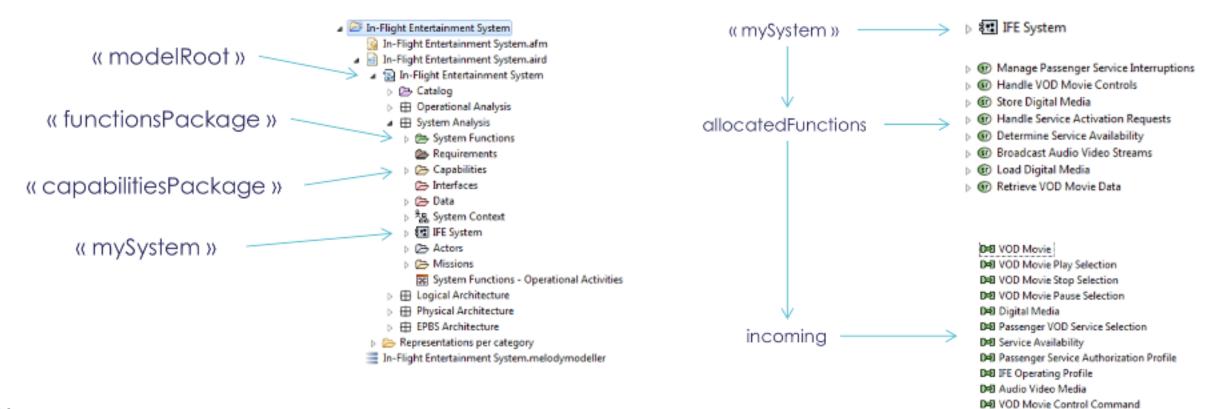


 A linguagem de modelo faz um uso extensivo da Acceleo Query Language, que fornece uma linguagem de consulta de modelo.

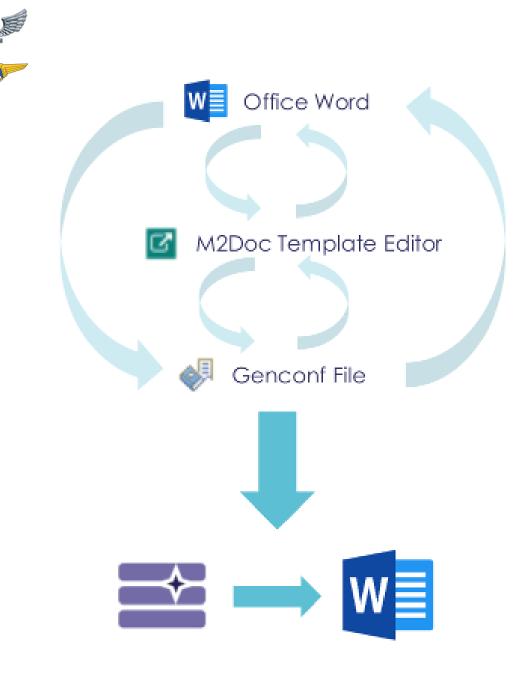
•Os modelos M2Doc podem ser validados. Se forem encontrados erros, um modelo anotado será produzido descrevendo os problemas encontrados.



- Definição dos pontos de entrada do modelo.
- Extração de informações navegando no modelo.



DEB Imposed Video Control Command



Definition of content, navigation, and format

Declaration of variables

Mapping of variables with model elements, definition of input model and output file

Generation of output document

Não é fácil e necessita de pessoas específicas:

- Template user: que já possuem o modelo e desejam gerar o documento.
 - Edita modelos e quer produzir documentos
- Template developer: que querem criar seu próprio modelo
 - Templates podem ser usados em diferentes documentos.
 - Varios templates podem ser usados em um modelo.
 - Conhece a estrutura de navegação AQL
- Integrator (Meta-model Expert): que desejam fornecer geração de documentos em seu próprio projeto usando M2Doc.
 - Cria serviços AQL para criadores de templates.



Básico de metamodelagem

https://www.eclipse.org/modeling/emf/



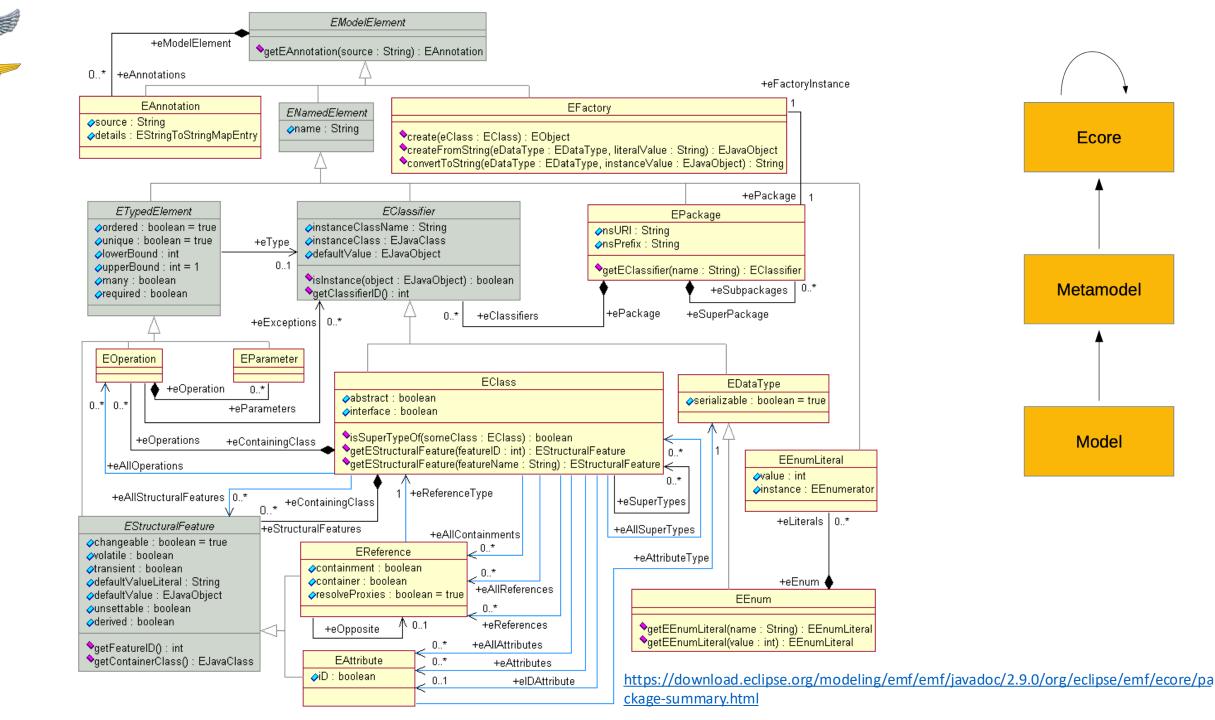
- EMF : Eclipse Modeling Framework
 - Modelagem de dados Java e framework de integração
- Fornece a infraestrutura para realmente usar os modelos em um aplicativo
- Facilmente acessível
- Open source EPL licence
 - Necessário conhecimento em Java
 - Aliás também em UML, XML Schema
 - Baseado em modelagem > geração de código
- Possibilita a produção rápida de modeladores
- Utiliza toda a facilidade trazida pelo Eclipse



- Um modelo EMF é um conjunto de dados
 - Conformação a um metamodelo
 - Composto por objetos com propriedades e relações
- Serializado em um arquivo XMI
- Conceitos próximos aos do diagrama de classes UML
 - Elements ~ Class
 - Attributes
 - References ~ Associations



- Um link entre o mundo do desenvolvimento e o mundo da modelagem
 - Converte modelos em código e vice-versa
 - Fornece toda a infraestrutura necessária de M / MM / M2M
- Gratuito
 - Licença EPL
 - Poucos pré-requisitos
 - Pode operar no modo autônomo (sem acesso externo)
- Estabilidade
 - Desenvolvido desde 2002
 - No centro da infraestrutura do Eclipse





Let's Talk

EMF Tutorial

🕚 24 min Read

What every Eclipse developer should know about EMF

This tutorial is an introduction to EMF and explains the basics of EMF. We start by showing you how to build a very simple data-centric application, including the UI, based on EMF. We explain how to define a model in EMF and generate code from it. We explore the API of the generated code, that is, how to create, navigate and modify model instances.

Next we demonstrate how to build a UI based on this model using databinding. For our example, we build an application to manage a bowling league, including matches and players. Later on in the tutorial, we explore the advantages of using AdapterFactories and briefly look at data management in EMF. We also include a few pointers on the most important add-on technologies for EMF. If you are interested in getting fast results building an application based on EMF, maybe <u>EMF Client Platform</u> is also a good starting point for you, see <u>this tutorial</u>.

PDF Download: This tutorial is also available for download as a PDF on our website.

Installation Requirements: To work through the examples, you'll need to download and install a fresh version of the Eclipse Modeling Tools from the Eclipse Download Page.

Introduction



Acceleo Query Language

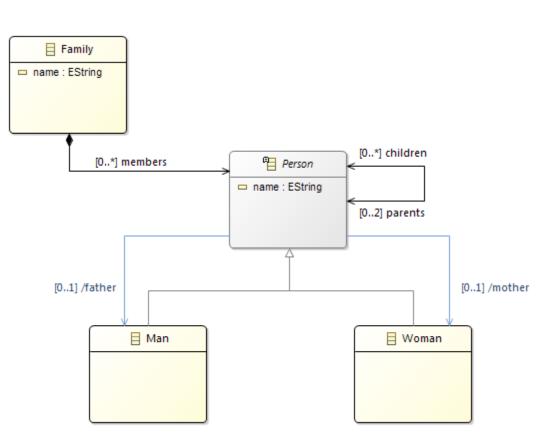


- A Acceleo Query Language (AQL) é uma linguagem usada para navegar e consultar um modelo EMF.
- O AQL como mecanismo de consulta é pequeno, simples, rápido, extensível e traz uma validação mais rica do que o interpretador MTL (Model to Text Language)
- O interpretador AQL é usado no Sirius com o prefixo «aql:»



From a variable one can access field or reference values using the . separator.

- With self being an instance of Person, self.name returns the value of the attribute name and self.father return the father of the person.
- If the attribute or the reference is multi-valued, then self.parents will return a collection.
- Calls can be chained, as such self.parents.name will return a collection containing the names of the parents.
- If one want to access the collection itself, then the separator -> must be used, as such self.parents.name->size() will return the number of elements in the collection whereas self.parents.name.size() will return a collection containing the sizes of each name.





- A noção de contexto
 - Uma consulta AQL se aplica ao seu contexto (denotado por "self")
- A navegação está em conformidade com o metamodelo usando a notação de pontos
 - Acesso a referências e atributos
 - Exemplo : aql:self.ownedSchemas.name
 - No contexto de um Banco de Dados, recupere os nomes dos esquemas de propriedade do banco de dados atual.



- Outros exemplos de consulta
 - aql:self.name in a Table context \rightarrow Name of the Table
 - aql:self.ownedTableElements.name in the context of

Table \rightarrow Column names list

• aql:self.ownedTableElements→size() in the context of a

Table \rightarrow Number of columns of the Table

- Elementos estáticos vs elementos dinâmicos
 - aql:'Table_ ' + self.name in the context of a Table named 'Vehicle' → "Table_Vehicle"
 - aql:'Prefixe' + self.name + 'Sufixe' → "PrefixeVehicleSufixe"

platform:/resource/fr.obeo.dsl.relational/model/relational.ecore
🔺 🌐 relational
a E Database -> ModelElement
url : EString
ownedSchemas: Schema
Schema -> ModelElement
a 🗧 Table -> ModelElement
ownedTableElements : TableElement
ForeignKey -> TableElement
Column -> TableElement
🔈 🖀 Type
a 🗧 ModelElement
name : EString
comment : EString
TableElement -> ModelElement

Estruturando as buscas: interpreter

- Disponível em Window > Show View > Interpreter
- Trabalha com representações do Sirius
- Mas também em todos os modelos EMF
- Muito útil para ajustar consultas



Acceleo Query Language

Query and navigate in EMF models

Overview

The Acceleo Query Language (AQL) is a language used to navigate and query an EMF model. In this document, you will find the description of all the services of the standard library of AQL.

Introduction

The Acceleo Query Language (AQL) is a language used to navigate and query an EMF model. In this document, you will find the description of the syntax, all the services and the standard library of AQL.

AQL as a query engine is small, simple, fast, extensible and it brings a richer validation than the MTL interpreter.

For those looking for a simple and fast interpreters for your EMF models, AQL can provide you with a lot of features, including:

- Support for static and dynamic Ecore models, no query compilation phase required.
- The least possible overhead at evaluation time. During this phase, the evaluation goes forward and will not even try to validate or compile your expressions. Errors are tracked and captured along the way.
- Strong validation: types are checked at validation time and the metamodels used are analyzed to do some basic type informed



(super) Pequeno exemplo...

https://www.m2doc.org/



- Primeiro você precisa baixar Capella.
- Quando o download estiver concluído, extraia o arquivo baixado e execute o executável Eclipse na subpasta Eclipse.

• INSTALLATION FOR CAPELLA 6.1.X

 https://s3-eu-west-1.amazonaws.com/obeonetworkaggregation-releases/capellaextensions/6.1.0_M2Doc3.3.0/full <u>zip</u> (M2Doc 3.3.0)



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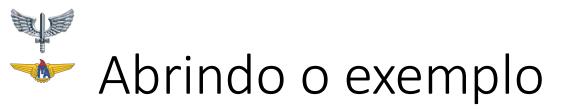
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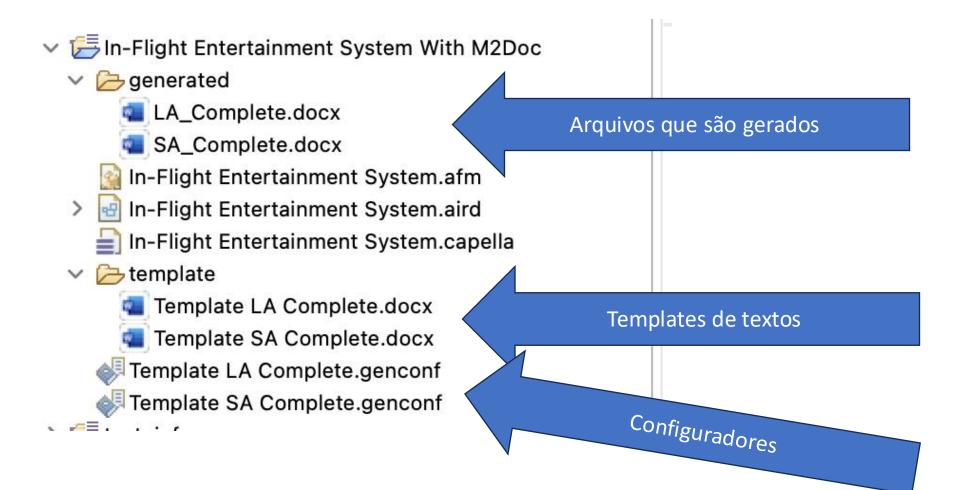
Select a wizard

associated Word templates.

Creates a sample project based on the IFE project , with M2Doc

82







ctrl+f9

Specification File of m:self.name p

3 → Description of the system Missions¶ ∰m:if self.containedSystemAnalysis.ownedMissionPkg.eAllContents(ctx::Mission)->size() > 0∰

§m:if self.containedSystemAnalysis.ownedMissionPkg.eAllContents(ctx::MissionPkg)->size() > 0
§
¶

The system Missions are sorted in the following packages:

Mission package	Missions
ईm:self.containedSystemAnalysis.ownedMission Pkg.name्वैः।	第:for mission ト self.containedSystemAnalysis.ownedMissionPkg. ownedMissions資目
	衛:mission.name.asBookmarkRef(mission.id) 劉 梁m:endfor難
m:for package self.containedSystemAnalysis.ov	vnedMissionPkg.eAllContents(ctx::MissionPkg)

(m:endfor)

(m:endfor)

(m:endif)

m:for mission | self.containedSystemAnalysis.ownedMissionPkg.eAllContents(ctx::Mission)

- 3.1→ <u>Mission::</u>∰m:mission.name.asBookmark(mission.id)) <u>Description:</u>¶

if mission.description.trim().size() <> 0]

tim:mission.description.trim().fromHTMLBodyString().replaceLink(mission)

m:else

No description ¶

(m:endif)

¶

Involved actors:

#m:if mission.involvedSystemComponents->select(sc | sc.actor)->size() > 0)

\$
for actor | mission.involvedSystemComponents->select(sc | sc.actor)
}

Specification File of In-Flight Entertainment System^p

[•] 3 → Description of the system Missions¶

3.1 → <u>Mission:</u> Provide <u>Entertainement</u> Solutions¶ <u>Description:</u>¶

No description ¶

9

P

Involved actors:

- → ∦REF·c8b78c78-5b11-4fc0-87b7-3ca84622efea \h ∦¶
- → ∰REF·181a678c-dca9-46c1-9d18-b5a0c457c0de \h ∰

Exploited capabilities:

3.1.1 → <u>Capability:</u>Provide Moving-Map Services¶

Description:

[Wikipedia]←

A moving-map system is a real-time flight information video channel broadcast through to cabin project/video screens and personal televisions (PTVs). In addition to displaying a map that illustrates the position and direction of the plane, the system gives the altitude, airspeed, outside air-temperature, distance to the destination, distance from the origination point, and local time. The moving-map system information is derived in real time from the aircraft's flight computer systems.

Capability inclusion relations:

9

(PAGE)¶

Including capabilities	Current capability	Included capabilities
No including capability¤	Provide Moving-Map Services¤	No included capability

Capability extension relations:

Extended capabilities	Current capability	Extending capabilities
No∙extended capability ¤	Provide Moving-Map Services¤	No extending capability¤

Capability generalization relations:

Super capabilities	Current capability	Sub capabilities
শ		<u></u> ‡PAGE [§] ¶

 $Specification \cdot File \cdot of \cdot In - Flight \cdot Entertainment \cdot System ""$

3 → Description of the system Missions¶

3.1→<u>Mission:</u>·Provide·<u>Entertainement</u>Solutions¶ Description:¶

No description¶

¶

Alt+f9

Involved actors:

- → Aircraft
- → Passenger¶
- ¶

Exploited capabilities:

• 3.1.1 → <u>Capability:</u>:Provide:Moving-Map:Services¶ <u>Description:</u>¶

[Wikipedia]

A moving-map system is a real-time flight information video channel broadcast through to cabinproject/video screens and personal televisions (PTVs). In addition to displaying a map that illustratesthe position and direction of the plane, the system gives the altitude, airspeed, outside airtemperature, distance to the destination, distance from the origination point, and local time. The moving-map system information is derived in real time from the aircraft's flight computer systems.

9

Capability inclusion relations:

Including capabilities	Current capability	Included capabilities
No including capability¤	Provide Moving-Map Services	No∙included capability¤

Capability extension relations:

Extended capabilities	Current capability	Extending capabilities
No∙extended capability¤	Provide Moving-Map Services	No-extending-capability¤
9		

Capability generalization relations:

Super capabiliti	es	Current capability	Sub capabilities	
				8¶